

Basics of Communication - Information Theory

Monica Navarro, Stephan Pfletschinger

Centre Tecnològic de Telecomunicacions de Catalunya (CTTC)

Wireless Networks: From Energy Harvesting to Information Processing

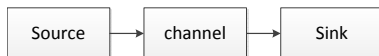
European School of Antennas/WIPE-COST ACTION IC1301
9 – 13 Nov. 2015, Castelldefels, Spain



- Introduction
- Basic Concepts of Information Theory
 - Entropy and mutual information
 - Fundamental channel models
- Capacities of Single-User Channels
 - BSC, BEC
 - AWGN, AWGN with discrete input
 - Fading channels

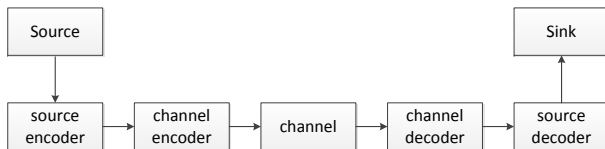
Communication System

- Lets consider the simplified representation of a communication system
- Goal: achieve reliable transmission; recover (at the sink) the transmitted information from the source with as little distortion as possible.



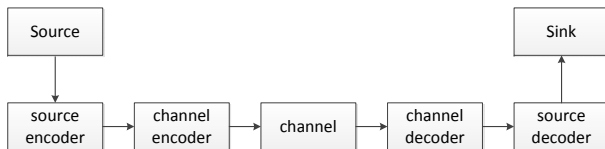
Communication System

- Lets consider the simplified representation of a communication system
- Goal: achieve reliable transmission; recover (at the sink) the transmitted information from the source with as little distortion as possible.
- source-channel separation theorem



Communication System

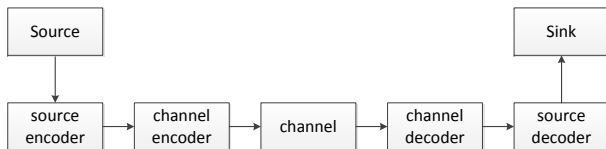
- Lets consider the simplified representation of a communication system
- Goal: achieve reliable transmission; recover (at the sink) the transmitted information from the source with as little distortion as possible.
- source-channel separation theorem



source coding theorem: for a given source and distortion measure, there exists a minimum rate $R(d)$ necessary (and sufficient) to describe this source with distortion $\leq d$.

Communication System

- Lets consider the simplified representation of a communication system
- Goal: achieve reliable transmission; recover (at the sink) the transmitted information from the source with as little distortion as possible.
- source-channel separation theorem

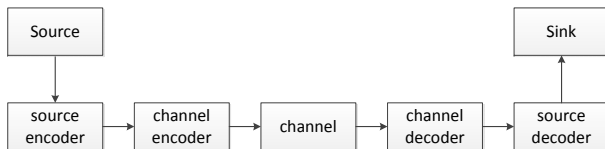


source coding theorem: for a given source and distortion measure, there exists a minimum rate $R(d)$ necessary (and sufficient) to describe this source with distortion $\leq d$.

channel coding theorem: there exist a maximum rate (bits per channel use) at which information can be transmitted reliably (probability of error $\rightarrow 0$) over a given channel. \Rightarrow maximum rate: **capacity** of the channel C .

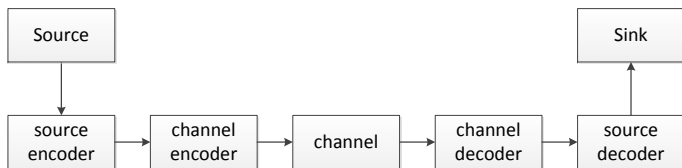
Communication System

- Lets consider the simplified representation of a communication system
- Goal: achieve reliable transmission; recover (at the sink) the transmitted information from the source with as little distortion as possible.
- source-channel separation theorem



Communication System

- Lets consider the simplified representation of a communication system
- Goal: achieve reliable transmission; recover (at the sink) the transmitted information from the source with as little distortion as possible.
- source-channel separation theorem



the source can be reconstructed at the receiver with a distortion of at most d if $R(d) < C$

- The performance limits for channel coding are given by the channel capacity
- Results from information theory are mathematically exact, but have to be interpreted with caution:
 - channel capacity holds for infinite block length
 - channel models are highly simplified
 - decoding complexity is not considered
- Nevertheless useful to obtain guidelines for practical design

Basic Concepts of Information Theory

Entropy and Mutual Information

We consider a discrete random variable $X \in \mathbb{X} = \{x_1, x_2, \dots, x_N\}$, where \mathbb{X} denotes an alphabet of cardinality N . The **probability mass function** (pmf) is denoted by

$$p_i = p(x_i) = P[X = x_i], \quad \text{with } \sum_{i=1}^N p_i = 1$$

The **entropy** of the X is defined as

$$H(X) = \sum_{x \in \mathbb{X}} p(x) \text{ld} \frac{1}{p(x)} = \mathbb{E}_X[-\text{ld} p(X)] \quad (1)$$

- logarithms are base two (“logarithmus dualis”), the entropy is measured in bits
- $H(X)$ depends only on the distribution of X , i.e. the p_i , and not on the values of X itself, i.e. the x_i

Entropy and Mutual Information

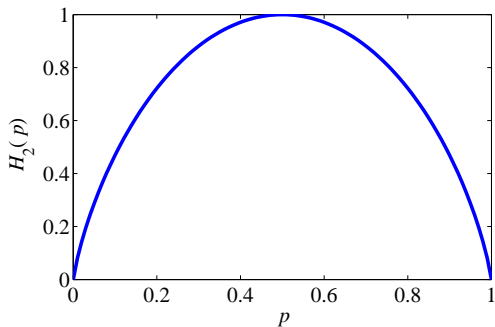
- We can think of the entropy $H(X)$ as a measure of
 - the amount of “information” provided by an observation of X
 - our “uncertainty” of X
 - the “randomness” of X
- Properties of $H(X)$
 - 1 $0 \leq H(X) \leq \log N$
 - 2 $H(X) = 0$ iff $p_i = 1$ for some i
 - 3 $H(X) = \log N$ iff $p_i = 1/N$ for all i
 - $H(X)$ vanishes only if X is deterministic and it is maximum if X is uniformly distributed

Binary entropy function

For $\mathbb{X} = \{0, 1\}$, $P[X = 0] = p$, we define

$$H_2(p) \triangleq -p \log p - (1 - p) \log(1 - p) \quad (2)$$

- $H_2(p)$ is a concave function in p
- attains its maximum at $p = 1/2$
- our uncertainty about a binary random variable is maximum if both outcomes are equiprobable



Entropy and Mutual Information

Multiple Random Variables

Now we consider two discrete RV, $X \in \mathbb{X}$ and $Y \in \mathbb{Y}$ and define the **joint entropy** and the **conditional entropy**

$$H(X, Y) = - \sum_{x \in \mathbb{X}} \sum_{y \in \mathbb{Y}} p(x, y) \text{ld} p(x, y) = -\mathbb{E} [\text{ld} p(X, Y)] \quad (3)$$

$$H(X|Y) = \sum_{y \in \mathbb{Y}} p(y) H(X|Y = y) = - \sum_{x \in \mathbb{X}} \sum_{y \in \mathbb{Y}} p(x, y) \text{ld} p(x|y) \quad (4)$$

where $H(X|Y = y) \triangleq - \sum_{x \in \mathbb{X}} p(x|y) \text{ld} p(x|y)$

The conditional entropy $H(X|Y)$ is our uncertainty about X after having observed Y .

Entropy and Mutual Information

Some properties of entropy

- Conditioning reduces entropy:

$$H(X|Y) \leq H(X) \quad (5)$$

- equality holds if and only if X and Y are independent
- $H(X|Y = y)$ can be greater than $H(X)$, but on the average the knowledge of Y reduces our uncertainty of X
- Chain rule

$$H(X, Y) = H(X) + H(Y|X) \leq H(X) + H(Y) \quad (6)$$

$$H(\mathbf{X}) \leq \sum_{i=1}^n H(X_i) \quad (7)$$

where $\mathbf{X} = (X_1, X_2, \dots, X_n)$

- The **mutual information** between X and Y is

$$I(X; Y) = \sum_{x \in \mathbb{X}} \sum_{y \in \mathbb{Y}} p(x, y) \text{ld} \frac{p(x, y)}{p(x)p(y)} \quad (8)$$

$$= H(X) - H(X|Y) \quad (9)$$

$$= H(X) + H(Y) - H(X, Y) \quad (10)$$

- $I(X; Y) \geq 0$ with equality iff X and Y are independent
- $I(X; Y)$ is the reduction in uncertainty of X due to the knowledge of Y
- If X is transmitted over a channel and received as Y , $I(X; Y)$ is the transmitted amount of information

- Mutual information for random vectors

$$\begin{aligned} I(X_1, X_2; Y) &= H(X_1, X_2) - H(X_1, X_2|Y) \\ I(\mathbf{X}; Y) &= H(\mathbf{X}) - H(\mathbf{X}|Y) \end{aligned} \quad (11)$$

- Conditional mutual information

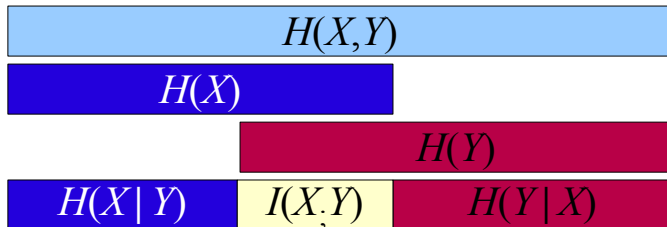
$$I(X; Y|Z) = H(X|Z) - H(X|Y, Z) = \sum_{z \in \mathcal{Z}} p(z) I(X; Y|Z = z) \quad (12)$$

- Chain rule

$$\begin{aligned} I(X_1, X_2; Y) &= I(X_1; Y) + I(X_2; Y|X_1) \\ &= I(X_2; Y) + I(X_1; Y|X_2) \end{aligned} \quad (13)$$

Entropy and Mutual Information

Relationship between entropy, conditional entropy, joint entropy and mutual information.



Entropy and Mutual Information

For a continuous random variable, we can define the **differential entropy**

$$h(X) \triangleq - \int p(x) \ln p(x) dx \quad (14)$$

The **conditional differential entropy** and the mutual information are defined accordingly

$$h(X|Y) = - \iint p(x, y) \ln p(x|y) dx dy \quad (15)$$

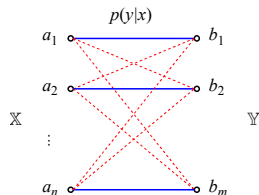
$$I(X; Y) = h(X) - h(X|Y) \quad (16)$$

- $h(X)$ might be negative
- $h(X)$ for a discrete random variable is $-\infty$
- $I(X; Y) \geq 0$ like in the discrete case
- chain rules hold like in discrete case

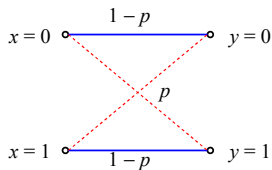
Basic Channel Models

Discrete memoryless channel

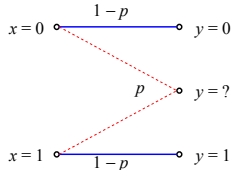
- The **discrete memoryless channel (DMC)**
 - is defined by an input alphabet \mathbb{X} , an output alphabet \mathbb{Y} and the transition probabilities $p(y|x)$
 - **memoryless** means $p(\mathbf{y}|\mathbf{x}) = \prod_{i=1}^n p(y_i|x_i)$
 - The simplest examples are the binary symmetric channel (BSC) and the binary erasure channel (BEC)



Binary symmetric channel



Binary erasure channel

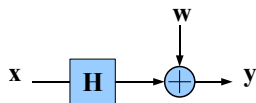
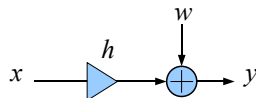
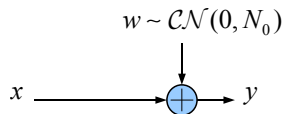


Basic Channel Models

Single-user channels

The following channels have continuous inputs and outputs.

- AWGN channel: $y = x + w$
- Rayleigh fading channel: $y = h \cdot x + w$
- Vector Gaussian channel: $\mathbf{y} = \mathbf{H}\mathbf{x} + \mathbf{w}$

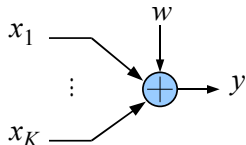


Basic Channel Models

Multi-user channels

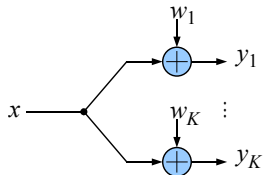
- Multiple-access channel (MAC)

- uplink
- K users
- K different messages
- K power constraints



- Broadcast channel (BC)

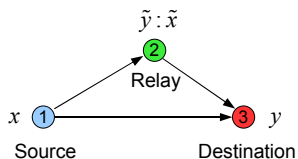
- downlink
- K users
- K different messages, one common message
- one power constraint



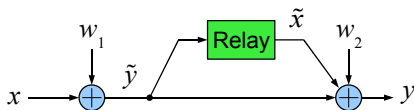
Basic Channel Models

Relay channel

- Relay channel, general model
 - Relay helps source to transmit its message
 - Capacity is unknown

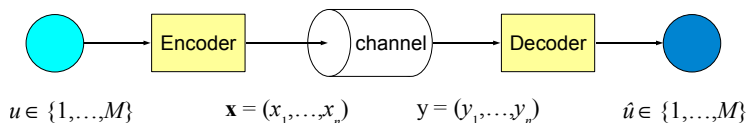


- Degraded Gaussian relay channel
 - Capacity is known



Single-User Channels

Definitions



An (n, M) **codebook** consists of

- an encoding function $u \rightarrow \mathbf{x} = (x_1, \dots, x_n)$
 - a decoding function $\mathbf{y} \rightarrow \hat{u}$

 - Probability of error: $P_e^n = P[u \neq \hat{u}]$
 - The rate $R = \frac{\log M}{n}$ is **achievable** if there exists a sequence of $(n, 2^{nR})$ codebooks such that $P_e^n \rightarrow 0$ for $n \rightarrow \infty$.
- \Leftrightarrow for every $\epsilon > 0$ we can find an $(n, 2^{nR})$ codebook such that $P_e^n < \epsilon$.

- Generate (n, M) codebook: $\mathcal{C} = \{\mathbf{x}(1), \mathbf{x}(2), \dots, \mathbf{x}(M)\}$
 - codebook is known to transmitter and receiver

$$\begin{pmatrix} x_1(1) & x_2(1) & \cdots & x_n(1) \\ x_1(2) & x_2(2) & \cdots & x_n(2) \\ \vdots & & & \vdots \\ x_1(M) & x_2(M) & \cdots & x_n(M) \end{pmatrix}$$

- Coding procedure
 - 1 Select message $u \in \{1, 2, \dots, M\}$
 - 2 Transmit $\mathbf{x}(u) = (x_1(u), x_2(u), \dots, x_n(u))$
 - 3 Receive $\mathbf{y} = (y_1, \dots, y_n)$
 - 4 Maximum likelihood decoding: $\hat{u} = \arg \max_i p(\mathbf{y}|\mathbf{x}(i))$

Capacities of Single-User Channels

- The **channel capacity** is the supremum of all achievable rates:

$$C = \sup R$$

Definition (Channel capacity)

The channel capacity of a channel with input X and output Y is given by

$$C = \max_{p(x)} I(X; Y)$$

Channel Capacity of BSC and BEC

- BSC (binary symmetric channel)

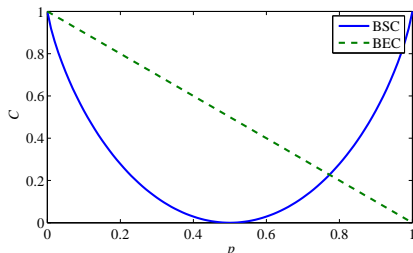
$$\begin{aligned} I(X; Y) &= H(Y) - H(Y|X) = H(Y) - \sum_{x \in \mathbb{X}} p(x) H(Y|X = x) \\ &= H(Y) - \sum_{x \in \{0,1\}} p(x) H_2(p) = H(Y) - H_2(p) \end{aligned}$$

- $H(Y)$ is maximum for $p_x = 1/2$, then $C_{\text{BSC}} = 1 - H_2(p)$

- BEC (binary erasure channel):

$$C_{\text{BEC}} = 1 - p$$

- on average, p bits get lost



Channel Capacity of the AWGN

- AWGN channel with continuous input:

$$\text{real-valued: } y = x + w, \quad x \in \mathbb{R}, \quad w \sim \mathcal{N}(0, N_0/2) \quad (17)$$

$$\text{complex-valued: } y = x + w, \quad x \in \mathbb{C}, \quad w \sim \mathcal{CN}(0, N_0) \quad (18)$$

- the capacities are

$$C_{\text{real}} = \frac{1}{2} \text{ld} \left(1 + \frac{2E_S}{N_0} \right), \quad C_{\text{complex}} = \text{ld} \left(1 + \frac{E_S}{N_0} \right) \quad (19)$$

- To achieve capacity, the channel input must be normal distributed:
 $x \sim \mathcal{N}(0, E_S)$ or $x \sim \mathcal{CN}(0, E_S)$.
- this holds for the discrete-time channel, capacity is measured in bits per channel use
- for the continuous-time channel, this corresponds to the spectral efficiency, measured in bps/Hz
- Note: $N_0 = 2\sigma^2$ by convention

Channel Capacity of the AWGN

Outline of derivation for real-valued AWGN

- Power constraint: $\mathbb{E}[x^2] \leq E_S$, mutual information:
 $I(X; Y) = h(Y) - h(Y|X)$

$$C = \max_{p(x): \mathbb{E}[x^2] \leq E_S} \{h(Y) - h(Y|X)\}$$

- the differential entropy of a $\mathcal{N}(\mu, \sigma^2)$ distributed random variable is $\frac{1}{2} \text{ld}(2\pi e\sigma^2)$, independent of μ . Then

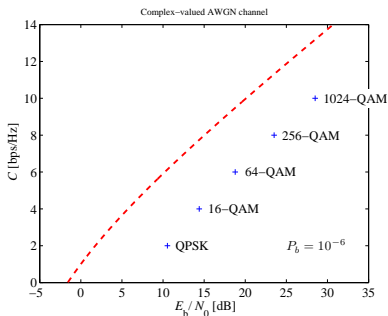
$$h(Y|X) = \int_{-\infty}^{\infty} p(x) h(\underbrace{Y|X=x}_{\sim \mathcal{N}(x, N_0/2)}) dx = h(W) = \frac{1}{2} \text{ld}(\pi e N_0)$$

- The normal distribution maximizes the differential entropy for a given second moment $\Rightarrow Y$ is normal distributed $\Rightarrow X \sim \mathcal{N}(0, E_S)$,
 $Y \sim \mathcal{N}(0, E_S + \frac{N_0}{2})$, $h(Y) = \frac{1}{2} \text{ld}(\pi e(2E_S + N_0))$ and finally

$$C = \frac{1}{2} \text{ld} \left(1 + \frac{2E_S}{N_0} \right)$$

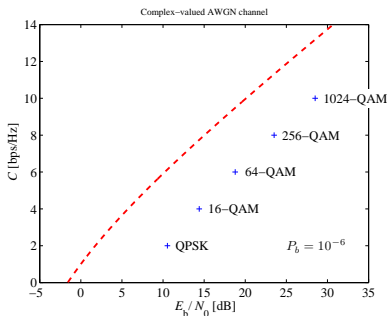
Channel Capacity of the AWGN

- Consider the real-valued AWGN with continuous input
 - E_S is the energy per transmitted symbol
 - in the context of channel coding, we often use the **energy per bit**
 $E_b = \frac{E_S}{R}$
 - the maximum rate is $R = \frac{1}{2} \log_2 \left(1 + \frac{2RE_b}{N_0} \right)$, thus $\frac{E_b}{N_0} = \frac{2^{2R} - 1}{2R}$
 - for $R \rightarrow 0$, $\frac{E_b}{N_0} \rightarrow \ln 2$, i.e. -1.59 dB



Channel Capacity of the AWGN

- Consider the real-valued AWGN with continuous input
 - E_S is the energy per transmitted symbol
 - in the context of channel coding, we often use the **energy per bit**
 $E_b = \frac{E_S}{R}$
 - the maximum rate is $R = \frac{1}{2} \log_2 \left(1 + \frac{2RE_b}{N_0} \right)$, thus $\frac{E_b}{N_0} = \frac{2^{2R} - 1}{2R}$
 - for $R \rightarrow 0$, $\frac{E_b}{N_0} \rightarrow \ln 2$, i.e. -1.59 dB
 - **For $E_b/N_0 < -1.59$ dB, no reliable transmission!**



Channel Capacity of Parallel AWGN Channels

- Consider N inputs X_1, X_2, \dots, X_N
- N outputs Y_1, Y_2, \dots, Y_N
- each with $Y_i = X_i + W_i, W_i \sim \mathcal{N}(0, \sigma_i^2)$
- subject to a total power constraint

$$\mathbb{E} \left[\sum_{i=1}^N X_i^2 \right] \leq P$$

- The capacity is given by

$$C = \sum_{i=1}^N \frac{1}{2} \text{ld} \left(1 + \frac{P_i}{\sigma_i^2} \right)$$

- is achieved for independent Gaussian $X_i \sim (0, P_i)$
- with $P_i = \max\{\nu - \sigma_i^2, 0\}, \nu$ a constant and $\sum_{i=1}^N P_i = P$

Channel Capacity of Parallel AWGN Channels

- Consider N inputs X_1, X_2, \dots, X_N
- N outputs Y_1, Y_2, \dots, Y_N
- each with $Y_i = X_i + W_i$, $W_i \sim \mathcal{N}(0, \sigma_i^2)$
- subject to a total power constraint

$$\mathbb{E} \left[\sum_{i=1}^N X_i^2 \right] \leq P$$

- The capacity is given by

$$C = \sum_{i=1}^N \frac{1}{2} \text{ld} \left(1 + \frac{P_i}{\sigma_i^2} \right)$$

- is achieved for independent Gaussian $X_i \sim (0, P_i)$
- with $P_i = \max\{\nu - \sigma_i^2, 0\}$, ν a constant and $\sum_{i=1}^N P_i = P$

→ Waterfilling

Channel Capacity of the AWGN with Discrete Input

- AWGN channel with discrete input
 - Transmit symbol (channel input) is taken out of a discrete alphabet, e.g. a PAM constellation: $x \in \mathbb{X} = \{a_1, a_2, \dots, a_M\} \subset \mathbb{R}$. We additionally assume that all constellation points are equiprobable.

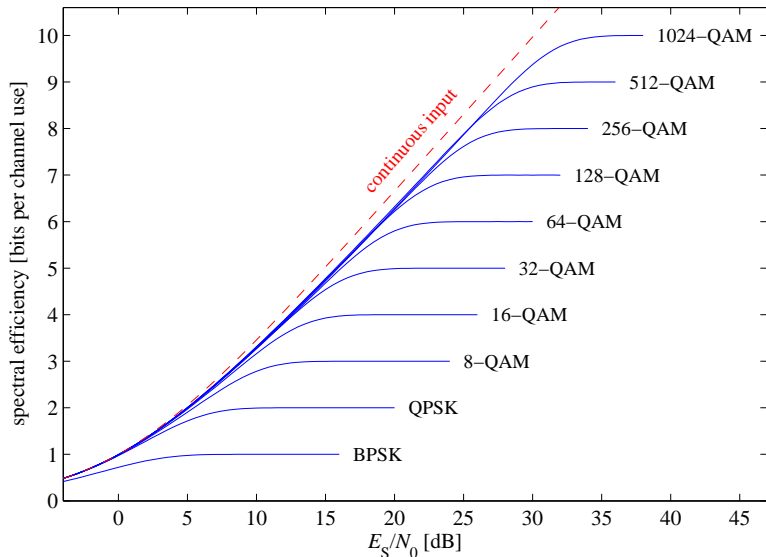
$$h(Y|X) = \sum_{x \in \mathbb{X}} p(x) h(Y|X = x) = h(W) = \frac{1}{2} \text{ld}(\pi e N_0)$$

$$h(Y) = -\mathbb{E}[\text{ld}p(y)] = -\mathbb{E}\left[\text{ld}\left(\frac{1}{M\sqrt{\pi N_0}} \sum_{i=1}^M \exp\left(-\frac{(y - a_i)^2}{N_0}\right)\right)\right]$$

$$C = h(Y) - h(Y|X)$$

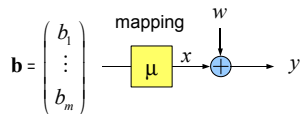
- Note: most QAM constellations can be separated into two PAM constellations

Channel Capacity of the AWGN with Discrete Input



Capacities of AWGN channel with QAM

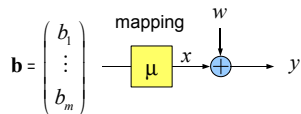
Definitions



- With little loss of generality, we consider real-valued constellations
- Definitions and assumptions for real-valued AWGN
 - channel: $y = x + w$, noise: $w \sim \mathcal{N}(0, N_0/2)$,
$$p(y|x) = \frac{1}{\sqrt{\pi N_0}} \exp\left(-\frac{(y-x)^2}{N_0}\right)$$
 - input bit vector: $\mathbf{b} = (b_1, \dots, b_m)^T \in \{0, 1\}^m$
 - mapping function: $\mu : \{0, 1\}^m \rightarrow \mathbb{X} = \{a_1, a_2, \dots, a_M\} \subset \mathbb{R}$, with $M = 2^m$
 - uniform input distribution: $P[b_i = 0] = 0.5 \forall i$, hence
$$P[x = a_i] = 2^{-m} = \frac{1}{M}$$

Capacities of AWGN channel with QAM

Definitions



- With little loss of generality, we consider real-valued constellations
- Definitions and assumptions for real-valued AWGN
 - channel: $y = x + w$, noise: $w \sim \mathcal{N}(0, N_0/2)$,
$$p(y|x) = \frac{1}{\sqrt{\pi N_0}} \exp\left(-\frac{(y-x)^2}{N_0}\right)$$
 - input bit vector: $\mathbf{b} = (b_1, \dots, b_m)^T \in \{0, 1\}^m$
 - mapping function: $\mu : \{0, 1\}^m \rightarrow \mathbb{X} = \{a_1, a_2, \dots, a_M\} \subset \mathbb{R}$, with $M = 2^m$
 - uniform input distribution: $P[b_i = 0] = 0.5 \forall i$, hence
$$P[x = a_i] = 2^{-m} = \frac{1}{M}$$
 - **No optimization over input distribution**

Capacities of AWGN channel with QAM

Definitions

- We can define the following capacities:
 - ① $C^{\text{CM}} = I(X; Y) = I(\mathbf{B}; Y)$, “coded modulation” capacity
 - ② $C_q^{\text{CM}} = I(B_q; Y | B_1 \cdots B_{q-1})$, CM subchannel capacity
 - ③ $C_q^{\text{BICM}} = I(B_q; Y)$, BICM subchannel capacity
 - ④ $C^{\text{BICM}} = \sum_{q=1}^m I(B_q; Y)$, BICM capacity
- Note: only C^{CM} is independent of the mapping μ
- Derivation of capacities

From the chain rule,

$$C^{\text{CM}} = I(B_1 \cdots B_m; Y) = \sum_{q=1}^m I(B_q; Y | B_1 \cdots B_{q-1}) = \sum_{q=1}^m C_q^{\text{CM}}$$

Capacities of AWGN channel with QAM

Derivation

again with chain rule,

$$C_q^{\text{CM}} = \underbrace{I(B_q \cdots B_m; Y | B_1 \cdots B_{q-1})}_{\triangleq R_{q-1}} - \underbrace{I(B_{q+1} \cdots B_m; Y | B_1 \cdots B_q)}_{=R_q}$$

$$\begin{aligned} R_q &= \sum_{(b_1 \cdots b_q) \in \{0,1\}^q} P[B_1 = b_1, \dots, B_q = b_q] \cdot I(B_{q+1} \cdots B_m; Y | b_1 \cdots b_q) \\ &= 2^{-q} \sum_{j=0}^{2^q-1} \underbrace{I(B_{q+1} \cdots B_m; Y | (b_1 \cdots b_q) = \text{bin}(j))}_{\triangleq R_{q,j}} \end{aligned}$$

$R_{q,j} = C(\mathcal{A}((b_1 \cdots b_q) = \text{bin}(j)))$, where $\mathcal{A}((b_1 \cdots b_q))$ denotes the subconstellation with bits b_1, \dots, b_q fixed and $C(\mathcal{A})$ is its capacity

⇒ we require the capacity $C(\mathcal{A})$

Capacities of AWGN channel with QAM

Derivation

For a discrete set $\mathcal{A} = \{a_1, \dots, a_M\}$ and equally probable constellation points, we have

$$\begin{aligned} C(\mathcal{A}) &= \frac{1}{M} \sum_{i=1}^M \int_{-\infty}^{\infty} p(y|a_i) \text{ld} \frac{p(y|a_i)}{\frac{1}{M} \sum_{j=1}^M p(y|a_j)} dy \\ &= \text{ld} M - \frac{1}{M} \sum_{i=1}^M \int_{-\infty}^{\infty} p(y|a_i) \text{ld} \sum_{j=1}^M \frac{p(y|a_j)}{p(y|a_i)} dy \\ &= \text{ld} M - \frac{1}{M} \sum_{i=1}^M \mathbb{E}_{y|a_i} \left[\text{ld} \sum_{j=1}^M \exp \left(-\frac{(y - a_i)^2 - (y - a_j)^2}{N_0} \right) \right] \end{aligned}$$

since the expectation is over $y = a_i + \sqrt{\frac{N_0}{2}} w$, with $w \sim \mathcal{N}(0, 1)$, we can write

$$C(\mathcal{A}) = \text{ld} M - \frac{1}{M} \sum_{i=1}^M \mathbb{E}_w \left[\text{ld} \sum_{j=1}^M \exp \left(-\frac{(a_i - a_j + \sqrt{\frac{N_0}{2}} w)^2 - \frac{N_0}{2} w^2}{N_0} \right) \right]$$

Capacities of AWGN channel with QAM

Derivation

- Finally, for numerical computation, we can approximate the expectation with a normally distributed sequence w_1, w_2, \dots, w_N for $N \rightarrow \infty$ and obtain

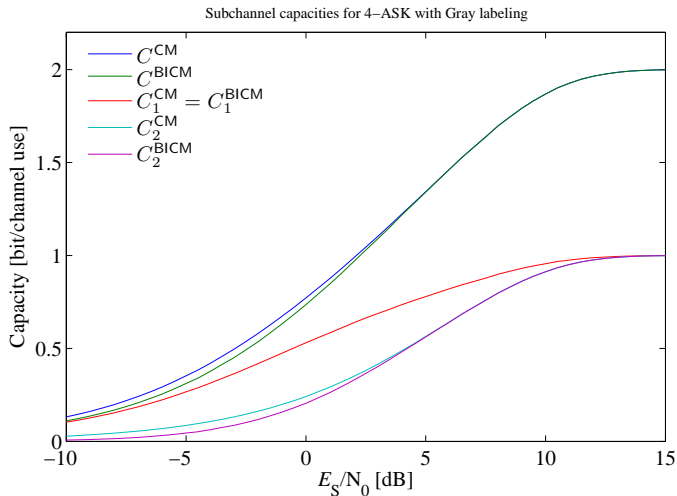
$$C(\mathcal{A}) \approx \text{ld} M - \frac{1}{NM} \sum_{n=1}^N \sum_{i=1}^M \text{ld} \sum_{j=1}^M \exp \left(-\frac{(a_i - a_j)^2}{N_0} + \sqrt{\frac{2}{N_0}} (a_i - a_j) w_n \right)$$

- Hence, we obtain $R_{q,j} \rightarrow R_q \rightarrow C_q^{\text{CM}}$. Note that we can compute C^{CM} directly.
- For BICM, we have the subchannel capacities

$$\begin{aligned} C_q^{\text{BICM}} &= I(\mathbf{B}; Y) - I(B_1 \cdots B_{q-1}, B_{q+1} \cdots B_m; Y | B_q) \\ &= C^{\text{CM}} - \frac{C(\mathcal{A}(b_q = 0)) + C(\mathcal{A}(b_q = 1))}{2} \end{aligned}$$

Capacities of AWGN channel with QAM

Capacities for 4-ASK with Gray labeling

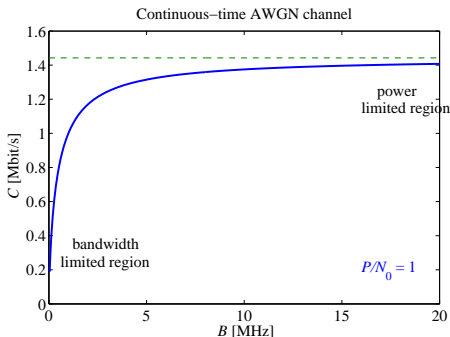


AWGN Capacity – Continuous Time

- We consider a passband channel with bandwidth B and noise power spectral density $N_0/2$ (note the redefinition of N_0 !). Its capacity in bit/s is

$$C = B \log \left(1 + \frac{P}{N_0 B} \right) \quad (20)$$

- The capacity for infinite bandwidth is $\lim_{B \rightarrow \infty} C = \frac{1}{\ln 2} \frac{P}{N_0}$



Fading Channels and Outage Capacity

- Flat fading channel: $y_i = h_i \cdot x_i + w_i$, $w_i \sim \mathcal{CN}(0, N_0)$
 - Power gain is unity, i.e. $\mathbb{E}[|h_i|^2] = 1$, e.g. Rayleigh fading: $h_i \sim \mathcal{CN}(0, 1)$
 - Average SNR is $\bar{\gamma} = \frac{E_s}{N_0}$
- Slow fading, no CSI at transmitter
 - channel coefficient is constant during one codeword: $h_i = h \forall i$, the “capacity” is hence $\text{ld}(1 + |h|^2 \bar{\gamma})$. The transmitter sends at rate R . The channel is in **outage** if the rate is too high,

$$P_{\text{out}}(R) = P[\text{ld}(1 + |h|^2 \bar{\gamma}) < R] = 1 - \exp\left(-\frac{2^R - 1}{\bar{\gamma}}\right)$$

Fading Channels and Outage Capacity

- Flat fading channel: $y_i = h_i \cdot x_i + w_i$, $w_i \sim \mathcal{CN}(0, N_0)$
 - Power gain is unity, i.e. $\mathbb{E}[|h_i|^2] = 1$, e.g. Rayleigh fading: $h_i \sim \mathcal{CN}(0, 1)$
 - Average SNR is $\bar{\gamma} = \frac{E_S}{N_0}$
- Slow fading, no CSI at transmitter
 - channel coefficient is constant during one codeword: $h_i = h \forall i$, the “capacity” is hence $\text{ld}(1 + |h|^2 \bar{\gamma})$. The transmitter sends at rate R . The channel is in **outage** if the rate is too high,

$$P_{\text{out}}(R) = P[\text{ld}(1 + |h|^2 \bar{\gamma}) < R] = 1 - \exp\left(-\frac{2^R - 1}{\bar{\gamma}}\right)$$

- **Channel capacity is zero!**
- We need another metric to describe this channel.

Fading Channels and Outage Capacity

- We define the **outage capacity** C_ϵ as the largest rate such that the outage probability is less than ϵ :

$$C_\epsilon = \text{ld} (1 + \bar{\gamma} \cdot F_g^{-1}(\epsilon)) \quad (21)$$

where $F_g(x) = P[g \leq x]$ is the cdf (cumulative distribution function) of the channel power gain $g = |h|^2$.

- Fast fading, no CSI at transmitter
 - h_i is i.i.d., while the codeword length $n \rightarrow \infty$. In this case, we apply the **ergodic capacity**

$$C = \mathbb{E} [\text{ld} (1 + |h|^2 \bar{\gamma})] \quad (22)$$

Remarks on practical Channel Coding schemes

Channel capacity and limits for infinite blocklength

- Shannon limit: reliable communication is only possible if the data rate is below the channel capacity
- For system design we may want to calculate the minimum SNR γ_{\min} required to achieve a target performance $\text{BER} = \rho$ with rate R
- Recall that for the Gaussian channel

$$y = x + w$$

with $w \sim \mathcal{N}(0, N_0/2)$

- capacity is achieved with Gaussian input distribution $x \sim \mathcal{N}(0, E_s)$

$$C_G(\gamma) = \frac{1}{2} \text{ld}(1 + 2\gamma)$$

- and the maximum achievable rate R for a given probability of bit error $p > 0$ is related to the channel capacity by

$$R(\gamma, p) = \frac{C_G(\gamma)}{1 - H_2(p)}$$

- where $H_2(p) = p \text{ld}(p) - (1 - p) \text{ld}(1 - p)$

$$\gamma_{\min, G} = \frac{1}{2} \left(2^{2R(1-H_2(p))} - 1 \right)$$

Channel capacity and limits for infinite blocklength

- Equivalently, for binary antipodal signalling $x \in \{+1, -1\}$ the capacity is

$$C_B(\gamma) = J(\sqrt{8\gamma})$$

with function $J(x)$ defined

$$J(x) = 1 - \frac{1}{\sqrt{2\pi}x} \int_{-\infty}^{\infty} \exp\left(-\frac{-(t - x^2/2)^2}{2x^2}\right) \text{ld}(1 + \exp(-t)) dt$$

- $J(x)$ and its inverse $J^{-1}(y)$ are typically calculated through numerical approximations [tenBrink01].
- The minimum SNR γ_{\min} required to achieve a target performance $\text{BER} = p$ with rate R with binary antipodal signalling is

$$\gamma_{\min, B} = \frac{1}{8} (J^{-1}(R(1 - H_2(p))))^2$$

- Curve fitting approximations of the $J(\cdot)$ -function

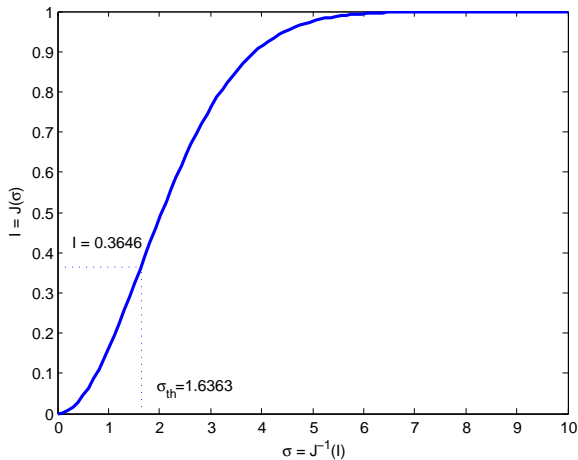
$$J(\sigma) = \begin{cases} -0.0421061\sigma^3 + 0.209252\sigma^2 - 0.00640081\sigma & 0 \leq \sigma \leq \sigma_{th} \\ 1 - \exp(0.00181491\sigma^3 - 0.142675\sigma^2 - 0.0822054\sigma + 0.0549608) & \sigma_{th} < \sigma < \infty \end{cases}$$

- Curve fitting approximations of the $J^{-1}(\cdot)$ -function

$$J^{-1}(I) = \begin{cases} 1.09542I^2 + 0.214217I + 2.33727\sqrt{I} & 0 \leq I \leq I_{th} \\ -0.706692 \ln(-0.386013(I - 1)) + 1.75017I & I_{th} < I < 1 \end{cases}$$

[tenBrink01] S.ten Brink, "Design of Concatenated Coding Schemes based on Iterative Decoding Convergence", PhD thesis, Apr. 2001.

- Approximation of the $J(\cdot)$ -function



Channel capacity and limits for finite blocklength

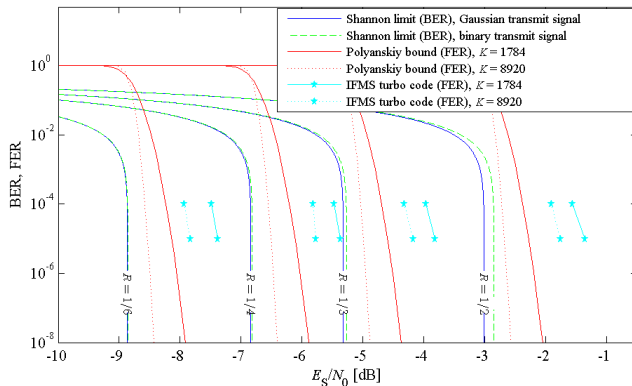
- However, practical communication systems use finite blocklength coding
- Polyanski, Poor and Verdú [Pol10] derived frame error probability bounds for finite length N schemes (Gaussian input distribution)
- The following expression provides a FER lower bound for any practical coding/decoding scheme

$$p_F \geq Q \left((1 + 2\gamma) \sqrt{\frac{N}{8\gamma(1 + \gamma)}} \left(\ln(1 + \gamma) + \frac{\ln N}{N} - 2R \ln N \right) \right)$$

[Pol10]Y. Polyanskiy, H. V. Poor, and S. Verd, Channel coding rate in the finite blocklength regime, IEEE Transactions on Information Theory, vol. 56, no. 5, pp. 2307-2359, May 2010.

Channel capacity and limits for finite blocklength

An example



Shannon limits for Gaussian and binary transmit signals, with Polyanskiy bound for codeword lengths $N = K/R_c$ and code rates $R_c = 1/2, 1/3, 1/4$ and $1/6$ and the performance of IFMS turbo codes.

- Today's channel coding schemes: LPDC, turbo-codes are capacity achieving for point to point BIAWGN channels
- There is room for improvement for multiuser networks
- But also for point to point links
 - short block lengths (e.g. Massive Machine Type Communications, IoT framework)
 - multi-terminal coding/decoding
 - improve computational power efficiency → transmission power efficiency to be expected
 - joint source-channel coding
 - security (network coding → physical layer security)